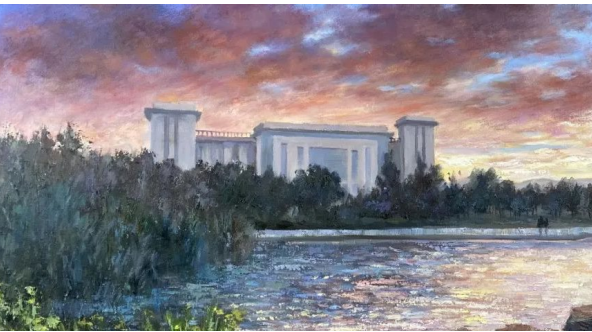


Uplink ISAC Receiver Designs

Receiver Design for Uplink ISAC

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Coauthors: Hong Ren, Cunhua Pan, Jiangzhou Wang**



Outline

- 1 Background
- 2 Conventional Receivers
- 3 Proposed Framework
- 4 Results and Outlook

Low-Altitude Economy

Emerging low-altitude application



- UAV video streaming and data uploading
- Environmental sensing and aerial monitoring
- Logistics, inspection, and airspace safety

Communication and sensing requirement



- Sustained **uplink transmission** for multimodal data
- ↕ **Same time and frequency?**
- **Continuous sensing** capability for surrounding targets

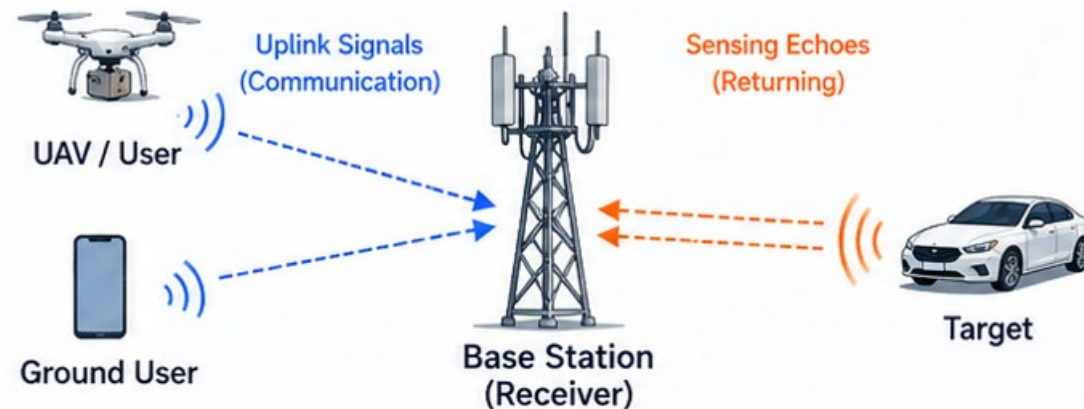
Comparison

Downlink ISAC: Transmitter-side design

**Research Focus:**

- Unified Waveform Design
- Sensing and Communication (S&C) **tradeoff**

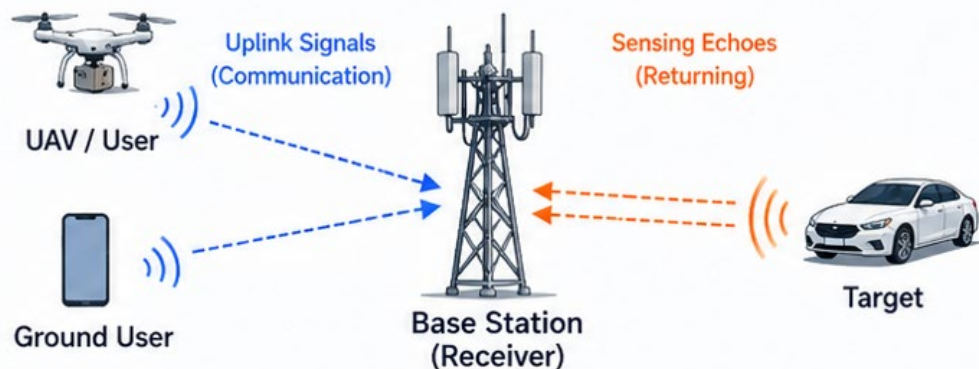
Uplink ISAC: Receiver-side Design

**Research Focus:**

- Signal Detection/ Parameter Estimation Algorithm
- S&C **mutual interference**

Key Point: How to decouple the S&C signal at the receiver in uplink ISAC?

System Model



Sensing signal

Commun. signal

$$\mathbf{Y} = \mathbf{H}_r \mathbf{X}_r + \mathbf{H}_c \mathbf{X}_c + \tilde{\mathbf{N}} \leftarrow \text{Noise}$$

- Sensing waveform: $\mathbf{X}_r = [\mathbf{x}_r[1], \dots, \mathbf{x}_r[L]]$ **Known**
- Target response matrix (TRM): \mathbf{H}_r **Unknown**
- Uplink data signal: $\mathbf{X}_c = [\mathbf{x}_c[1], \dots, \mathbf{x}_c[L]]$ **Unknown**
- Communication channel: \mathbf{H}_c **Known**

ML Estimation

$$\underset{\mathbf{H}_r, \mathbf{X}_c \in \mathcal{X}^{K \times L}}{\operatorname{argmin}} \left\| \mathbf{Y} - \mathbf{H}_r \mathbf{X}_r - \mathbf{H}_c \mathbf{X}_c \right\|_F^2$$

① ② ②

↓ Vectorized

$$\underset{\mathbf{h}_r, \mathbf{x}_c \in \mathcal{X}^{LK}}{\operatorname{argmin}} \left\| \mathbf{y} - \mathbf{A}_c \mathbf{x}_c - \mathbf{A}_r \mathbf{h}_r \right\|_2^2$$

Not a standard Least Square (LS) problem!

Main Challenges

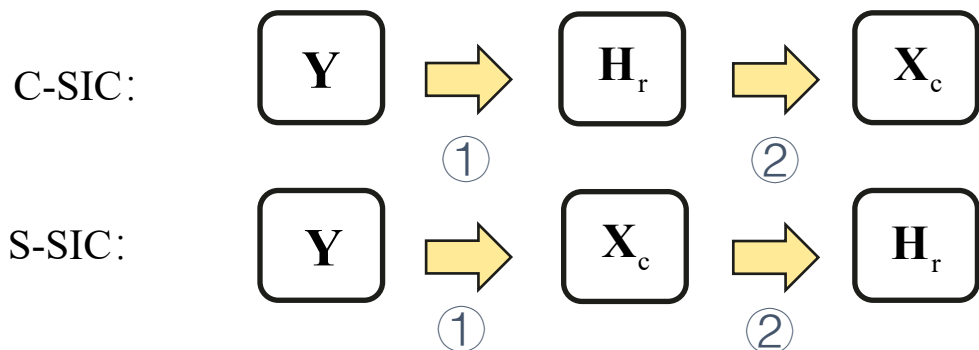
- ① **Mixed integer Programming:** Discrete communication signal and continuous TRM
- ② **Undetermined Property:** $\mathbf{AX} + \mathbf{YB} = \mathbf{C}$ does not provide unique solution $\tilde{\mathbf{X}}, \tilde{\mathbf{Y}}$ without ①. [1]

[1] A. Liao et.al., "Best approximate solution of matrix equation $\mathbf{AXB} + \mathbf{CYD} = \mathbf{E}$," SIAM Journal on Matrix Analysis and Applications, 2005

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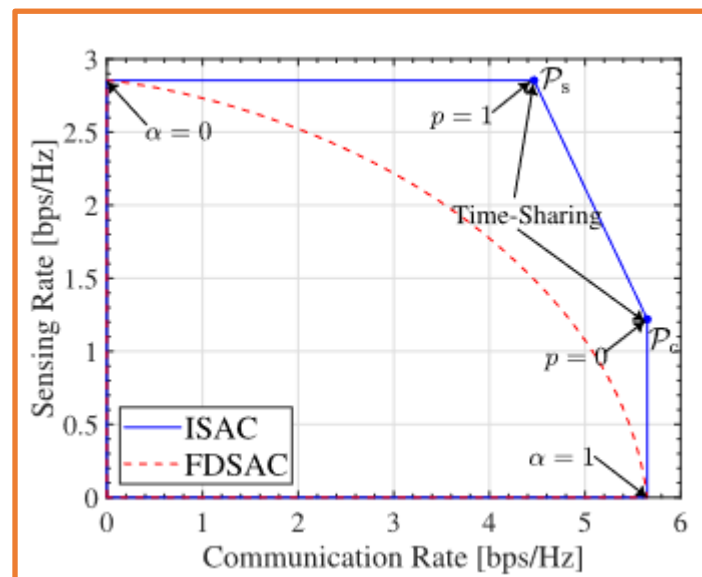
SIC-Type Receivers

SIC-Type Receivers_[2]

Take S-SIC as an example:

- ① The commun. signal is detected by **treating the sensing signal as AWGN**.
- ② The target response is estimated after subtracting the estimated commun. signal.

Pros and Cros



- Uplink ISAC **outperforms** frequent-division ISAC

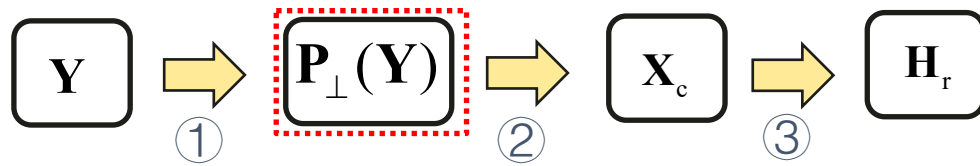
Drawbacks:

- Ineffective **mutual interference** cancellation
- Potential **error propagation**

Projection-type Receivers

Projection-Type Receivers_[2]

Design Pipeline



Exploit the **structure of the sensing signal** to fully eliminate its interference to signal detection

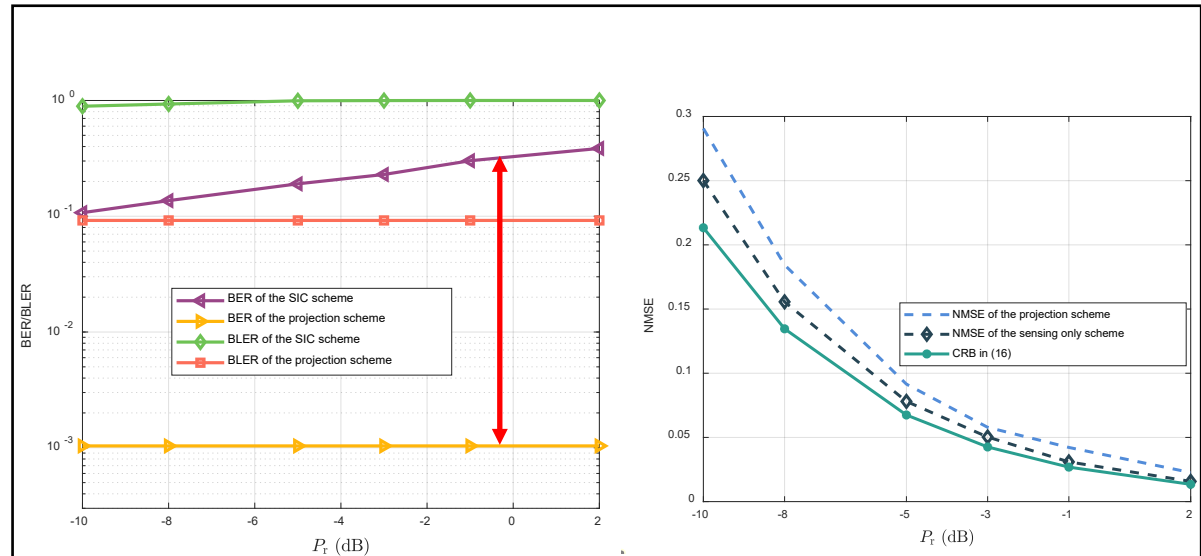


- Achieve the same SNR as the commun. only systems

$$\text{SNR}_p \triangleq \frac{\mathbb{E}[\|\Gamma \mathbf{A}_c \mathbf{x}_c\|_2^2]}{\mathbb{E}[\|\Gamma \mathbf{n}\|_2^2]} = \frac{P_c}{\sigma^2} = \text{SNR}_{\text{Com}}$$

- An **equivalent** formulation of ML estimation

Pros of the Projection-type receiver



- Lower BER due to the improved SNR
- Better Sensing performance due to the better communication signal detection in first stage

Projection-type Receivers

Cross of the Projection-type receiver

- Consider the signal detection problem after projection

$$\underset{\mathbf{x}_c \in \mathcal{X}^{LK}}{\operatorname{argmin}} \quad \|\tilde{\mathbf{y}} - \mathbf{G}\mathbf{x}_c\|_2^2 \quad \mathbf{G} = \mathbf{P}_\perp \otimes \mathbf{H}_c$$

Projection Matrix $\operatorname{Rank}(\mathbf{P}_\perp) = L - M_t$

The rank of the observation matrix is given by

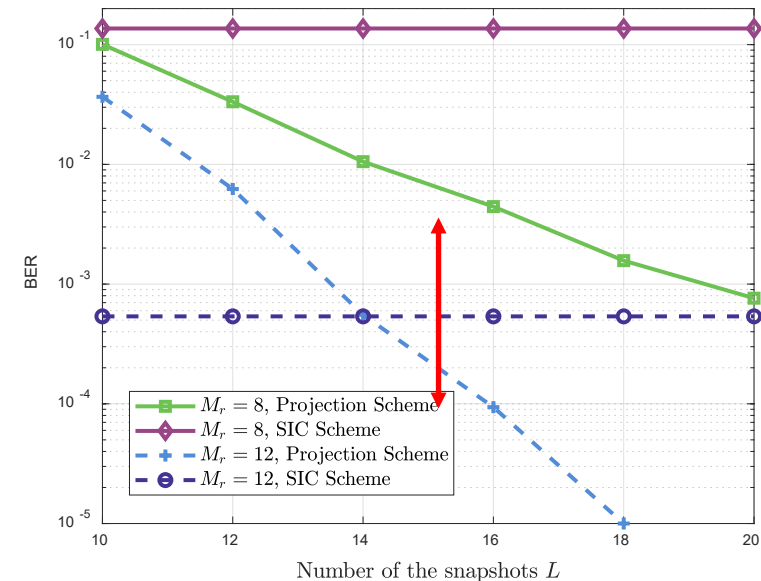
$$\operatorname{Rank}(\mathbf{G}) = (L - M_t)K < LK$$



- Signal Detection Algorithm

- Linear detectors, such as ZF, AMP, not applicable
- Other detectors, such as SDR, high complexity

Joint processing requirement



Jointly processing multiple snapshots is preferred, which leads to **higher computation complexity**.

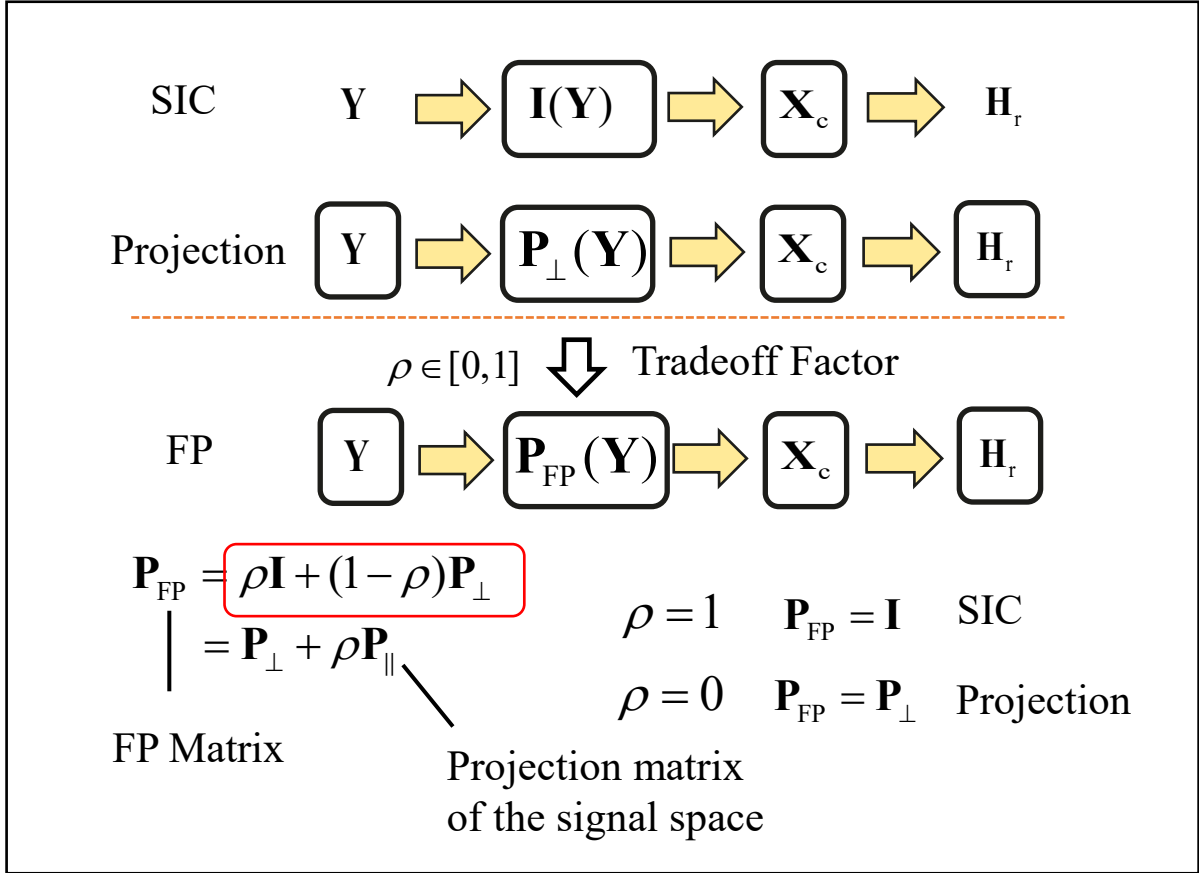
Attractive in theory, constrained in practice

Outline

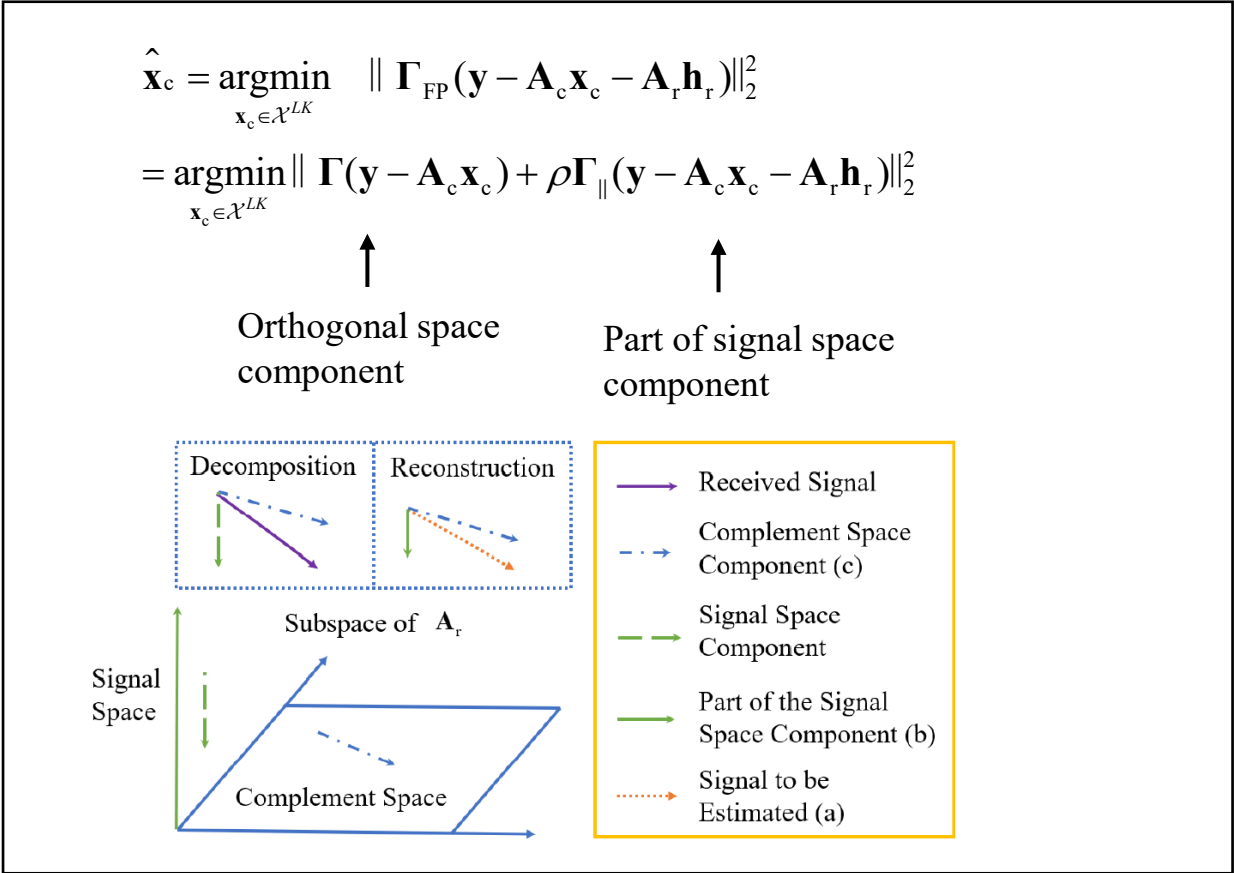
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FP-type Receiver

Flexible Projection(FP): A framework



Physical Illustration



Black or white is never optimal; balance is what we need

FP-type Receiver

SINR & Correlation Tradeoff

✓ SINR of the FP-type Receivers

$$\text{SINR}_{\text{FP}} \triangleq \frac{\mathbb{E}[\|\Gamma_{\text{FP}} \mathbf{A}_c \mathbf{x}_c\|_2^2]}{\mathbb{E}[\|\Gamma_{\text{FP}} \mathbf{A}_r \mathbf{h}_r\|_2^2] + \mathbb{E}[\|\Gamma_{\text{FP}} \mathbf{n}\|_2^2]}$$

$$= \frac{P_c(L - (1 - \rho^2)M_t)KM_r}{\rho^2LP_s + (L - (1 - \rho^2)M_t)M_rK\sigma^2}$$

Smaller ρ ,
larger SINR.

✓ Condition Number of the FP-type Receivers

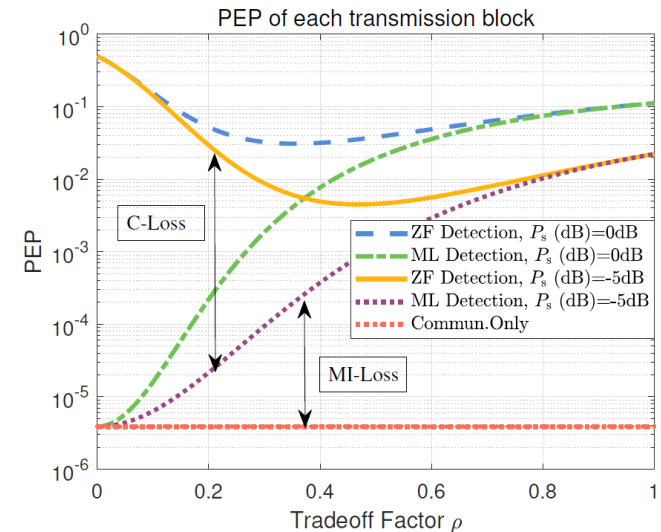
$$\text{Cond}_{\text{PT}}(\mathbf{G}_T) \triangleq \frac{\omega_1(\mathbf{G}_{\text{FP}})}{\omega_{L_N}(\mathbf{G}_{\text{FP}})} = \sqrt{\frac{\lambda_1(\mathbf{G}_{\text{FP}}^H \mathbf{G}_{\text{FP}})}{\lambda_{L_N}(\mathbf{G}_{\text{FP}}^H \mathbf{G}_{\text{FP}})}}$$

$$= \frac{\lambda_1(\mathbf{P}_{\text{FP}})}{\lambda_{L_N}(\mathbf{P}_{\text{FP}})} \text{Cond}(\mathbf{H}_c) = \frac{1}{\rho} \text{Cond}(\mathbf{H}_c)$$

Smaller ρ ,
smaller condition
number, larger column
correlations.

Pairwise Error Probability (PEP) Analysis

High-SNR approximation of BER curve



➤ ML Detector prefers small ρ , while ZF prefers larger.



Different ρ for different detection algorithm?

Finding the optimal tradeoff parameter is non-trivial

DFP-type Receiver

Design Philosophy

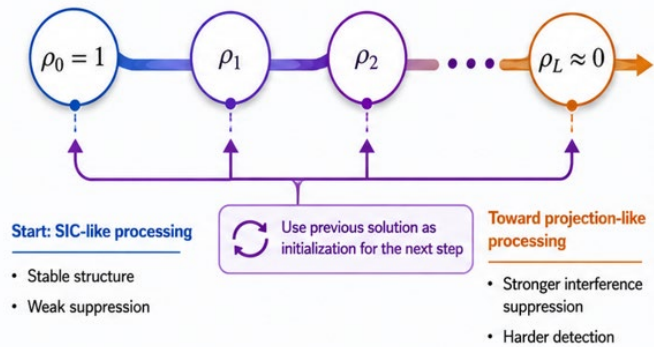
➤ Homotopy Optimization

Construct a family of Homotopy function

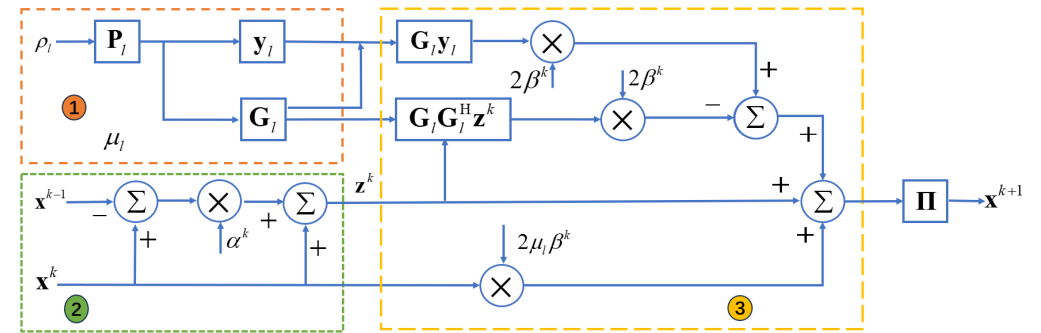
$$h(\mathbf{z}, \eta) = \begin{cases} \text{Easy Problem} \\ f^1(\mathbf{z}), & \text{if } \eta = 1 \text{ and} \\ \dots \\ f(\mathbf{z}) & \text{if } \eta = 0, \\ \text{Original Problem} \end{cases}$$

Approximate the original problem with a sequence of problems

➤ Dynamic Projection



Implement Detail



- ✓ Outer Layer **1**
Update penalty parameter μ and tradeoff factor ρ
- ✓ Inner Layer **2** **3**
Apply the gradient extrapolated majorization-minimization.



Only matrix multiplication evolved

Do the simple first, then do the right

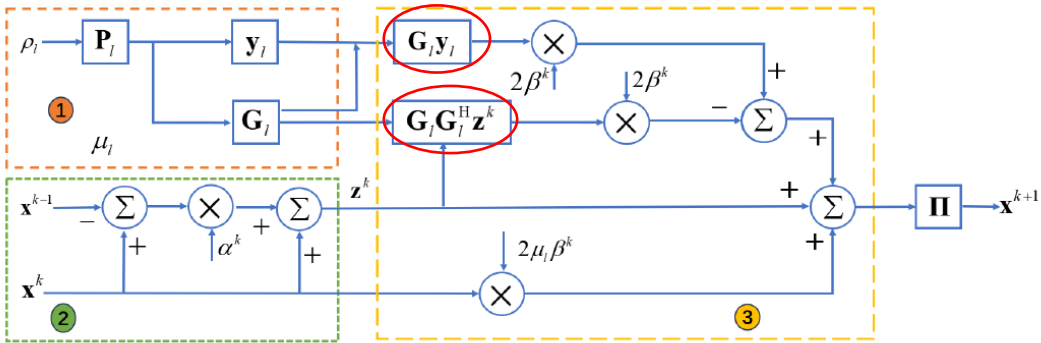
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Complexity of DFP

Complexity Reduction

Calculating the gradient of DFP requires the update of observation matrix.



➤ Solution: pre-calculation

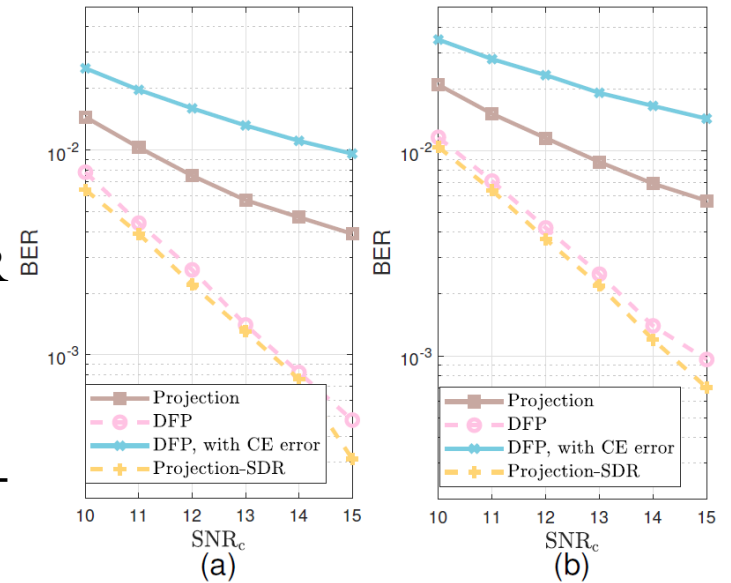
$$\mathbf{G}_l^T \mathbf{G}_l = (1 - \rho_l)^2 \mathbf{M}_1 + \rho_l (1 - \rho_l) \mathbf{M}_2 + \rho_l^2 \mathbf{M}_3,$$

$$\mathbf{G}_l^T \mathbf{y}_l = (1 - \rho_l)^2 \mathbf{u}_1 + \rho_l (1 - \rho_l) \mathbf{u}_2 + \rho_l^2 \mathbf{u}_3,$$

DFP-type receiver achieves the **same complexity as conventional projection-type receiver** via pre-calculation.

Performance Comparison

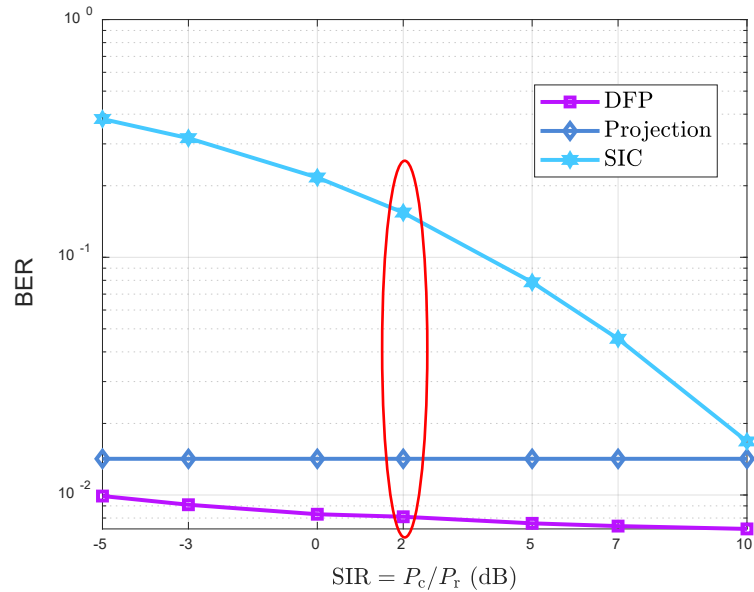
- Performance closes to projection-SDR
- CPU time **reduces 100x** than projection-SDR



(M_r, K, L)	DFP receiver	SIC receiver	Projection-SDR
(8, 8, 16)	0.0018	5.8×10^{-4}	0.55
(16, 16, 16)	0.0166	0.0025	2.52
(16, 16, 24)	0.0411	0.0025	Memory Limited

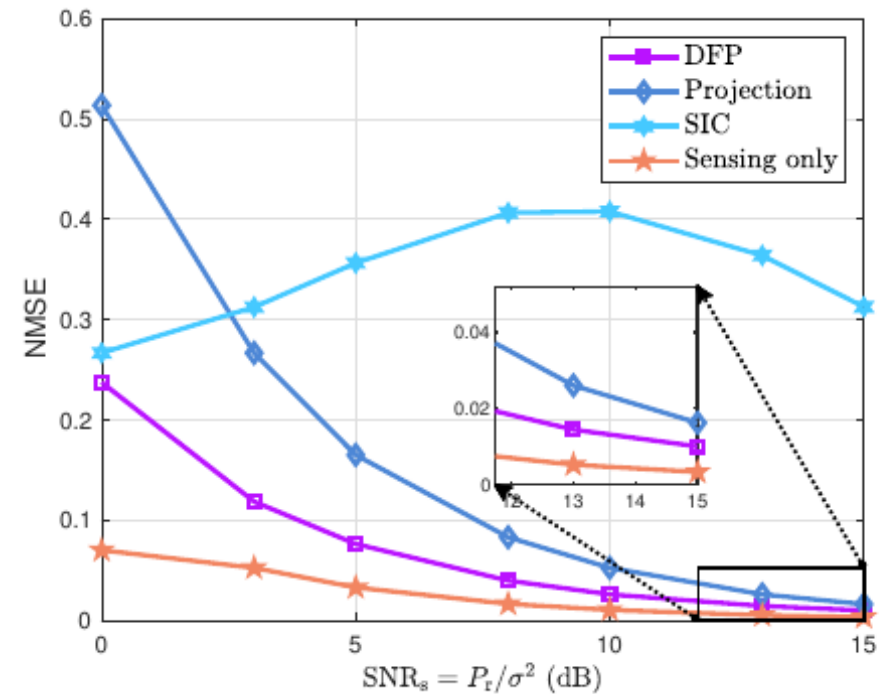
S&C Performance

BER of uplink transmission



DFP outperforms projection-type receiver and has much lower BER than SIC-type receiver.

NMSE of TRM Estimation



DFP has lower NMSE than benchmark, closes to the sensing-only systems in high SNR region.

S&C Performance

Angle Estimation for Bistatic ISAC setup

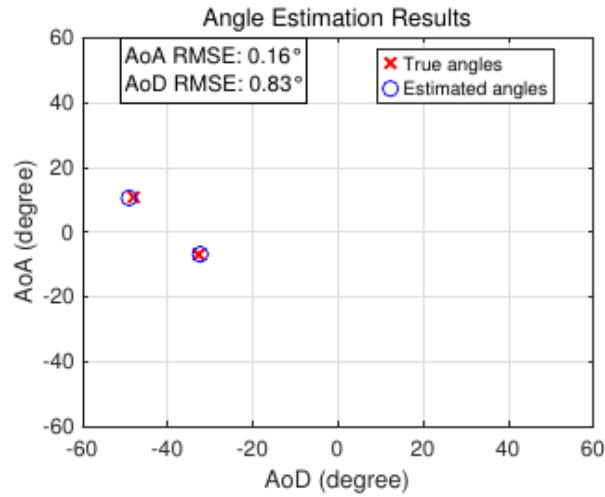


Fig. 9 (a): Sensing only, $M_t = N_r = K = 8$

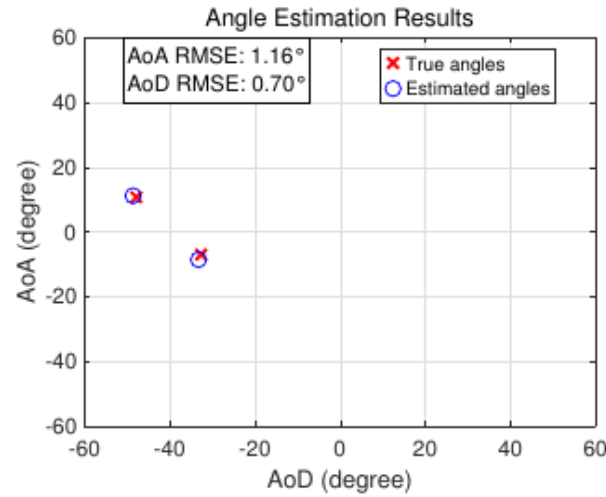


Fig. 9 (b): DFP, $M_t = N_r = K = 8$

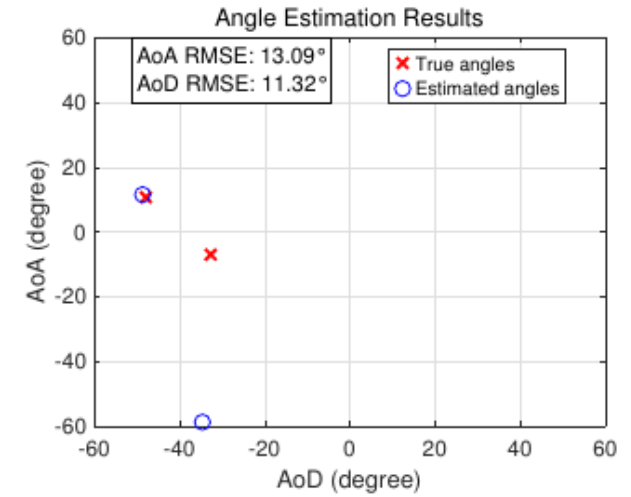


Fig. 9 (c): SIC, $M_t = N_r = K = 8$

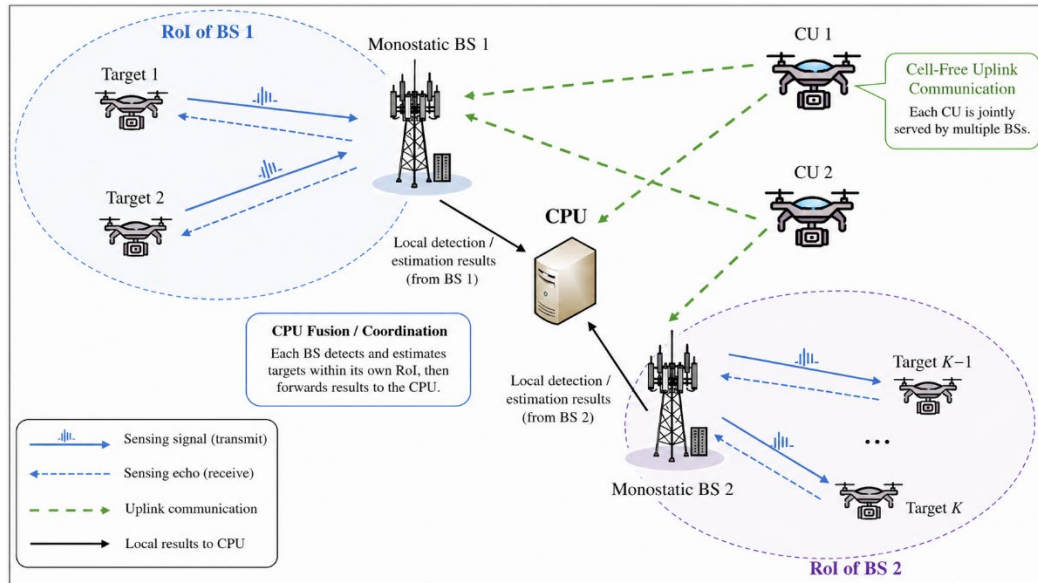
	DFP-type	SIC-type	Sensing-only
RMSE	5.6°	8.2°	2.2°
Hit rate	71.3%	50.9%	90.2%

Error < 2°

- Compared to the SIC receiver, the angle RMSE of DFP has reduced more than **40%**, and its hit rate has increased more than **20%**

Cell-free Uplink ISAC systems

Gain from the diversity



➤ The rank-deficient issue can be addressed in cell-free uplink ISAC

Learn from the environment

➤ Design the structure of the DFP-receiver using detection theory

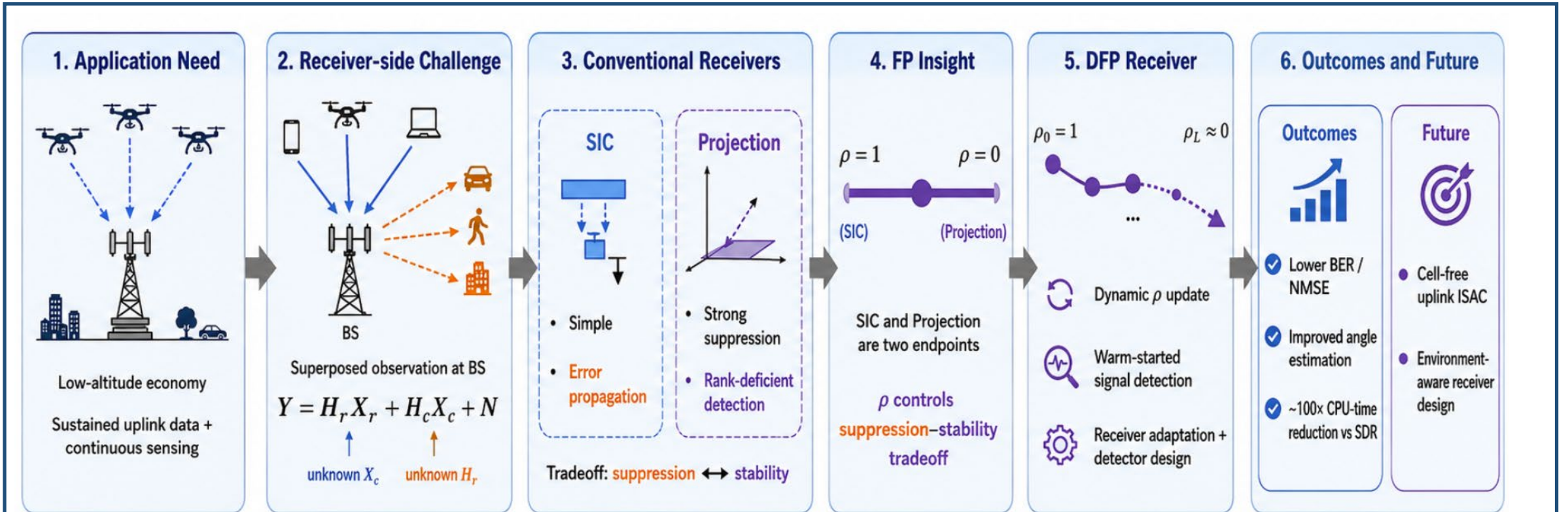
$$w_{1,k}^{(t)} = \frac{p(\mathbf{y}_k | z_k = 1, \mathbf{x}_c^{(t-1)})P(z_k = 1)}{p(\mathbf{y}_k | z_k = 1, \mathbf{x}_c^{(t-1)})P(z_k = 1) + p(\mathbf{y}_k | z_k = 0, \mathbf{x}_c^{(t-1)})P(z_k = 0)}$$

$$\Phi_k^{(t)} = \frac{1}{\sigma_k^2} \left[(1 - w_{1,k}^{(t)})\mathbf{I} + w_{1,k}^{(t)}\mathbf{\Gamma}_k \right]$$



The receiver can be **adjusted according to the received signal**

Take Away Message



➤ Related Paper

- [1] Z. Yu, H. Ren, C. Pan, G. Zhou, R. Wang, M. Liu, J. Wang, "Addressing the Mutual Interference in Uplink ISAC Receivers: A Projection Method," *IEEE Wireless Commun. Lett.*, vol. 13, no. 11, pp. 3109–3113, Nov. 2024.
- [2] Z. Yu, H. Ren, C. Pan, G. Zhou, D. Wang, J. Wang, "A Framework for Uplink ISAC Receiver Designs: Performance Analysis and Algorithm Development," *IEEE Trans. Wireless Commun.*, vol. 25, pp. 16628-16644, 2026.

Uplink ISAC Receiver Designs

**Thanks for your Listening!
Any Questions?**

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